

Learning CY metrics

FABIAN RUEHLE
Physics meets ML
April 21st, 2021

Based on:

[Anderson, Gray, Gerdes, Krippendorf, Raghuram, FR: 2012.04656]

[Larfors, Lukas, FR: 1805.08499]

[Ashmore, FR: 2103.07472]



Outline

Motivation
for
String Theory

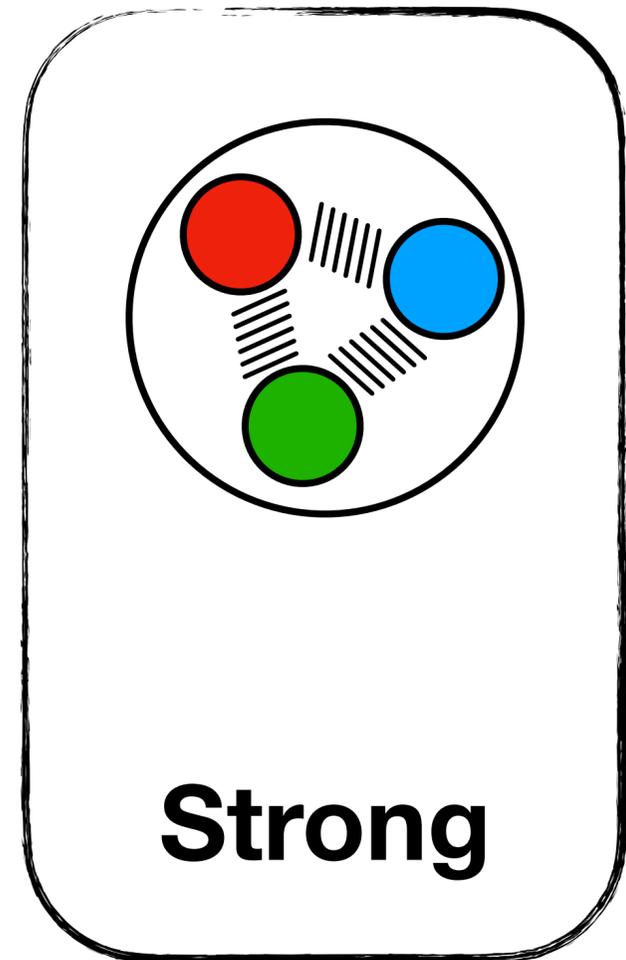
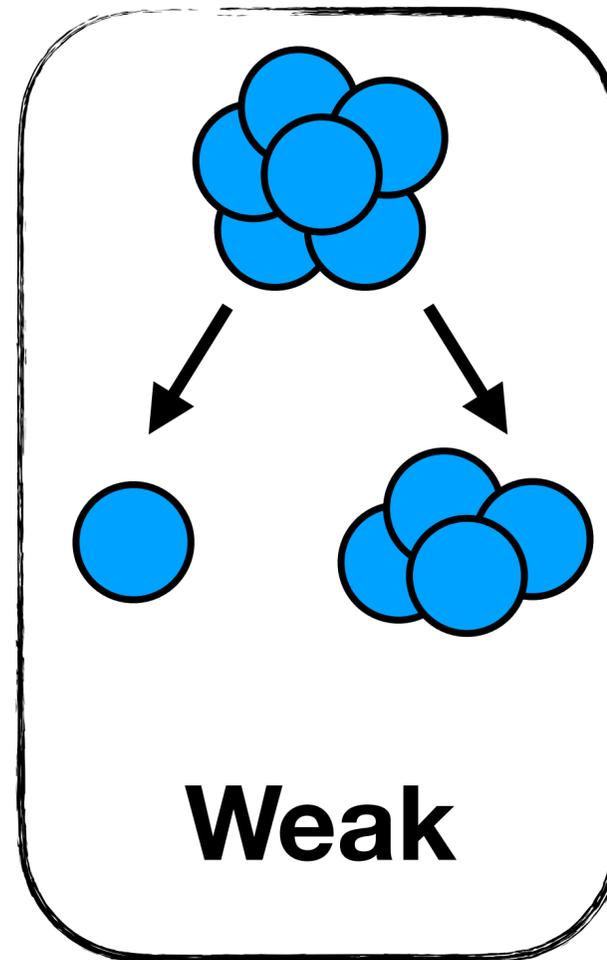
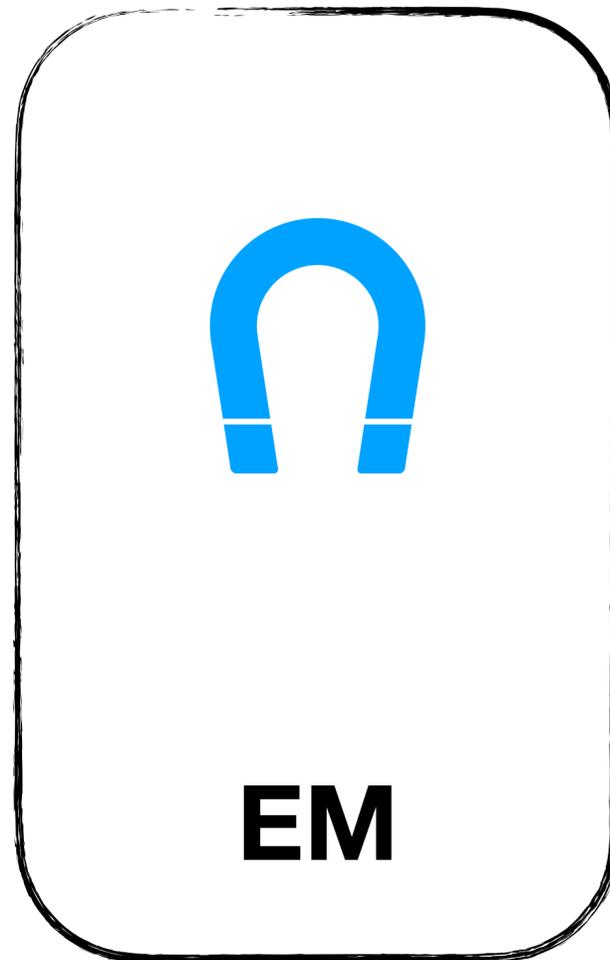
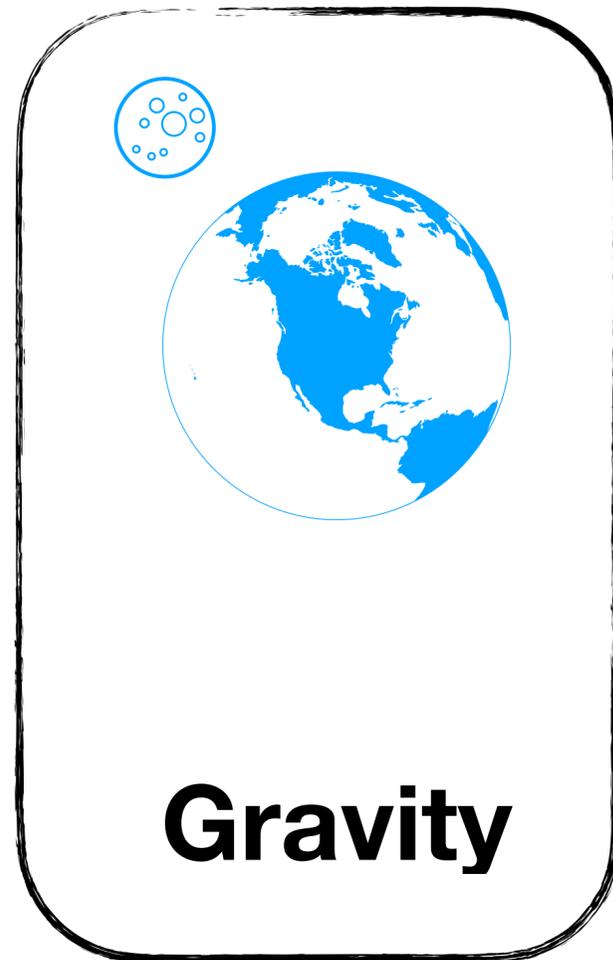
Metrics

Calabi-Yau
Manifolds

ML for CY
Metrics

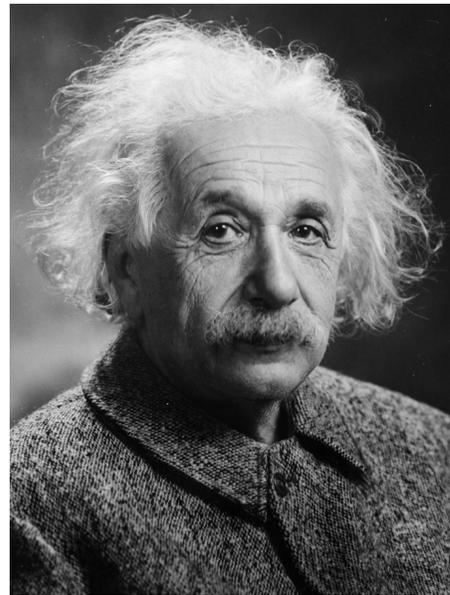
Fundamental interactions

Many observations in our Universe can be explained with just four fundamental forces

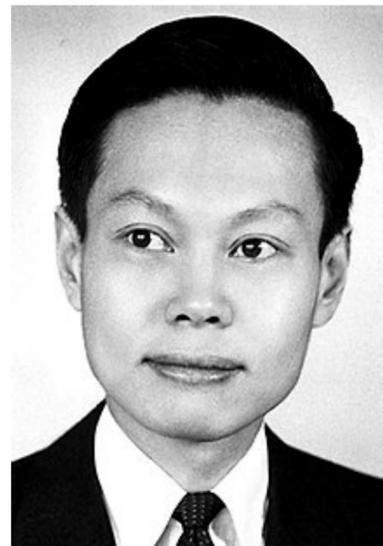


Fundamental interactions

Two theories to describe these four forces.

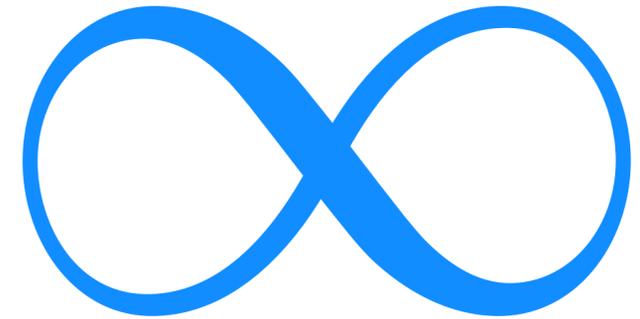
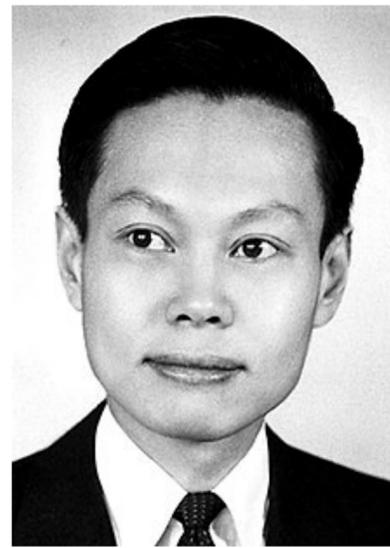
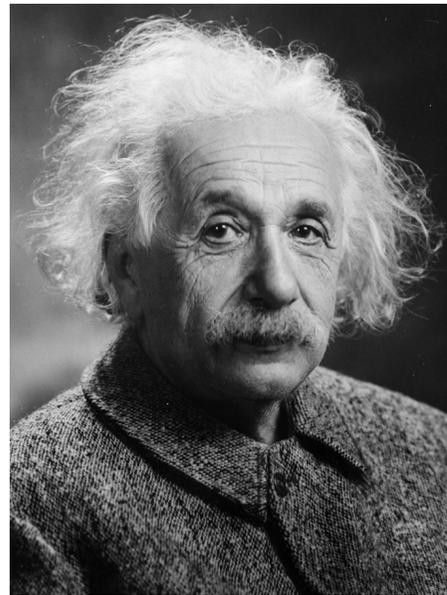


**General
Relativity**



**Quantum Field Theory
(Yang-Mills Theory)**

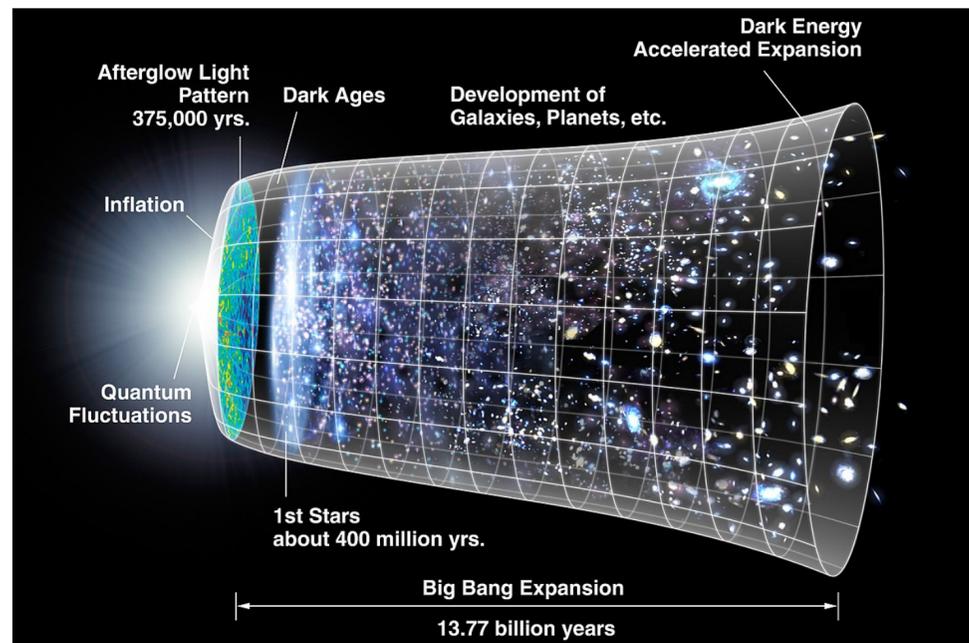
Fundamental interactions



“... so don't combine them”

Combining the descriptions

...however, we need a unified description to study physics at high energies

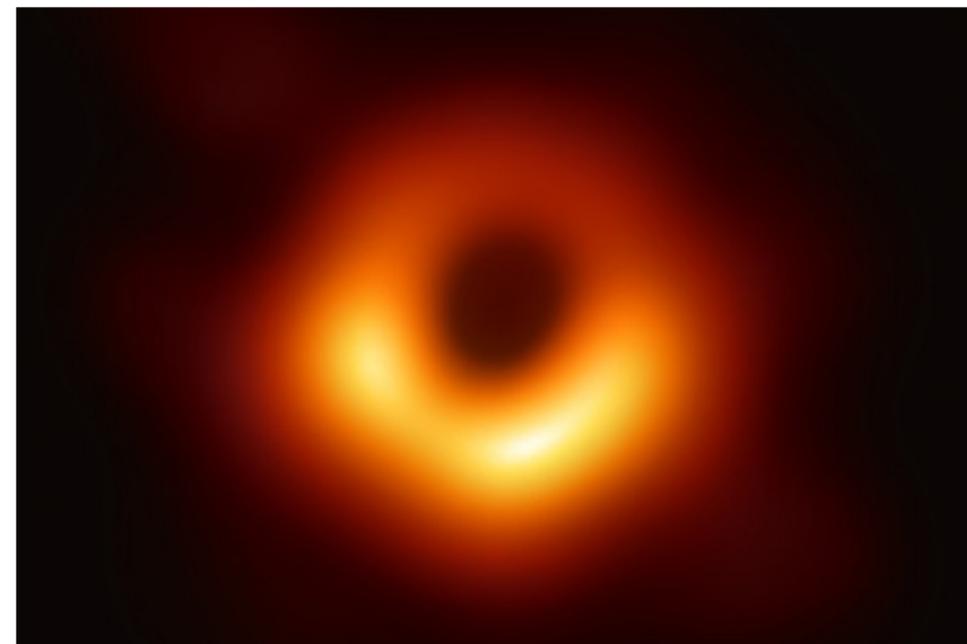
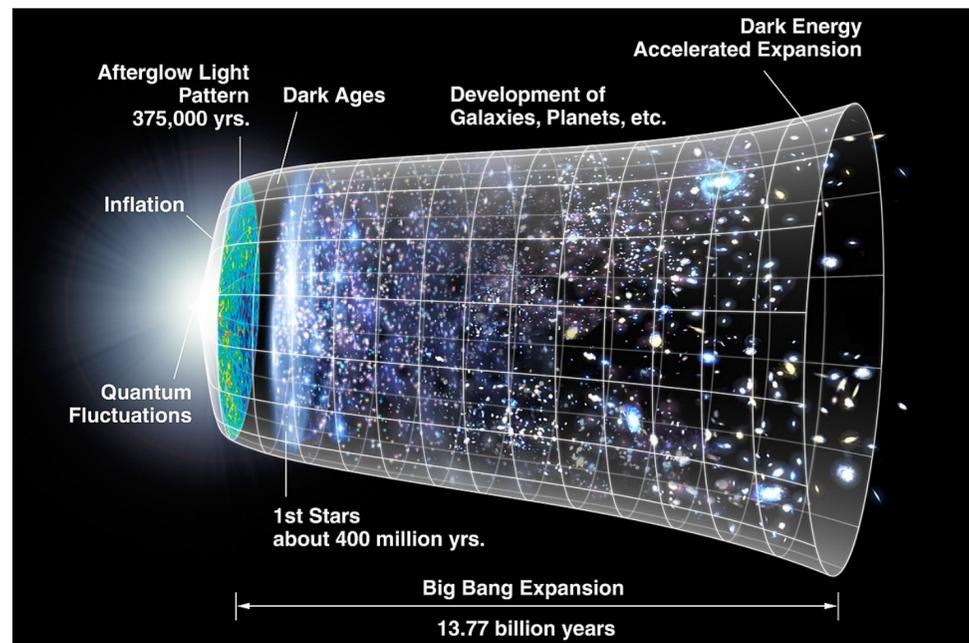


What happened at
the Big Bang?

What is Dark Energy?

Combining the descriptions

...however, we need a unified description to study physics at high energies

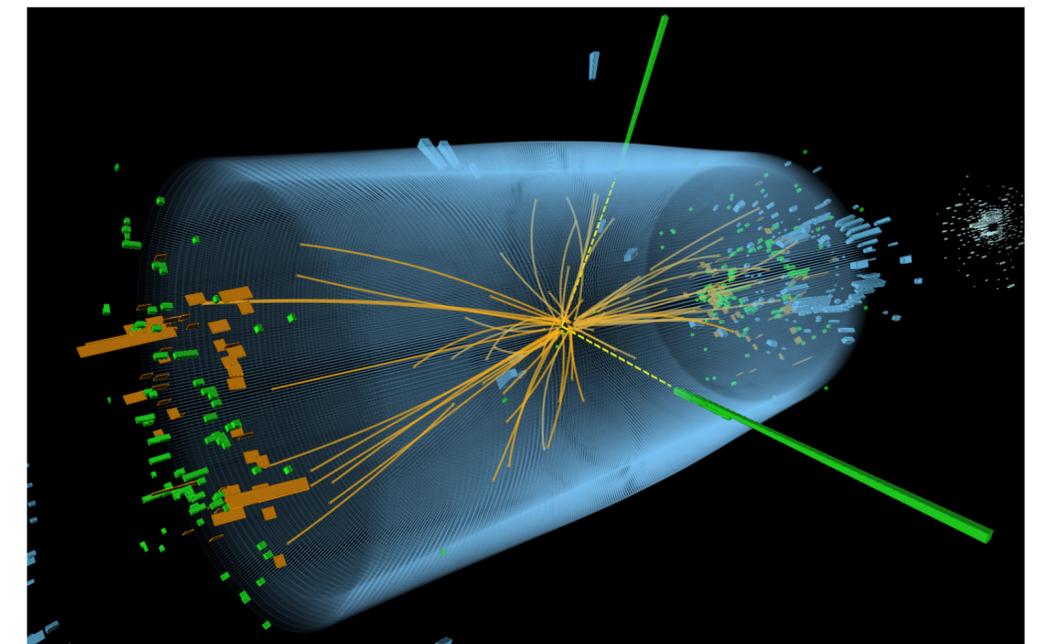
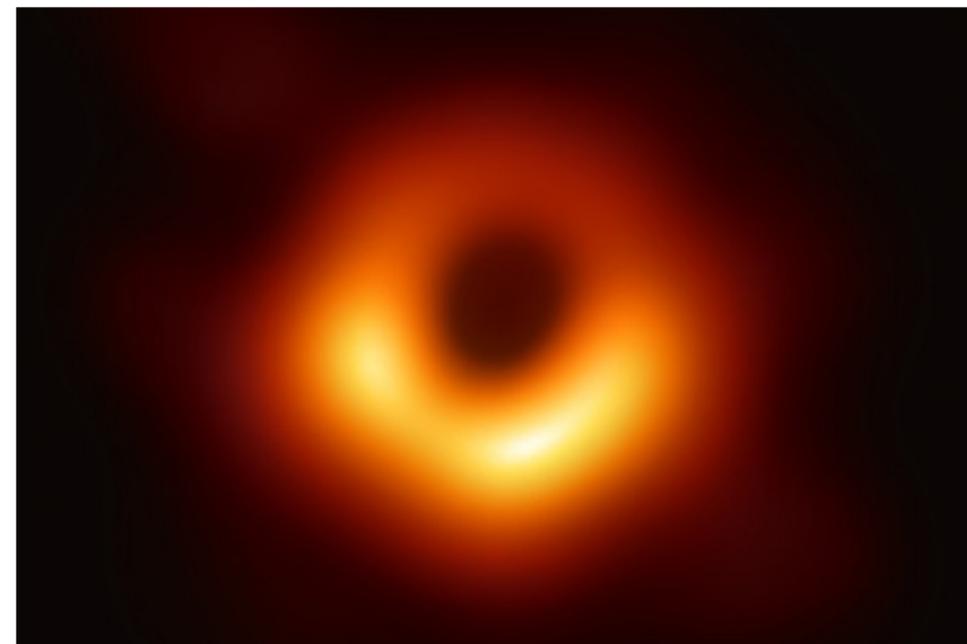
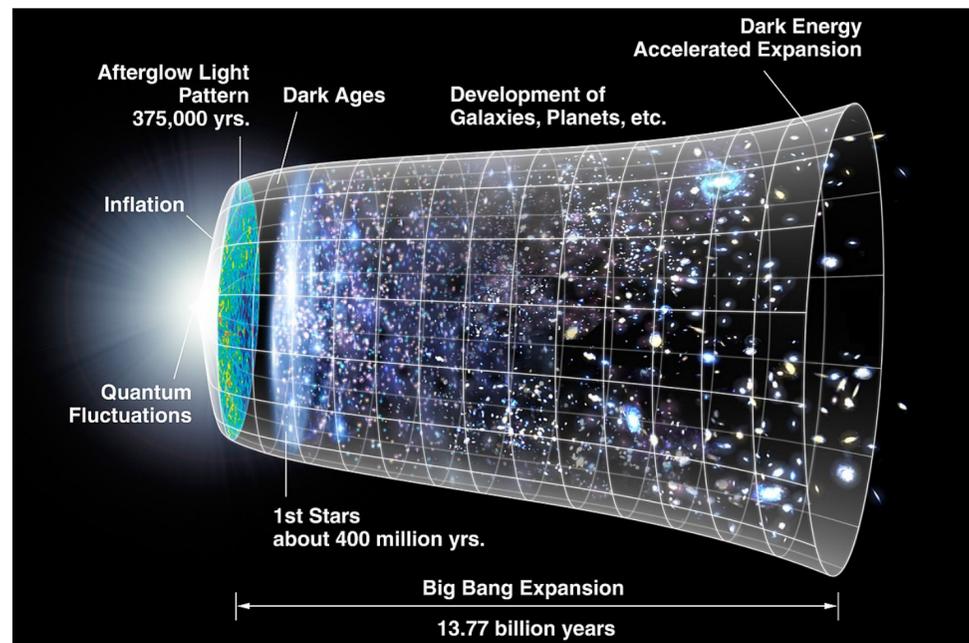


What happened at
the Big Bang?
What is Dark Energy?

What happens at the
event horizon of a
black hole?

Combining the descriptions

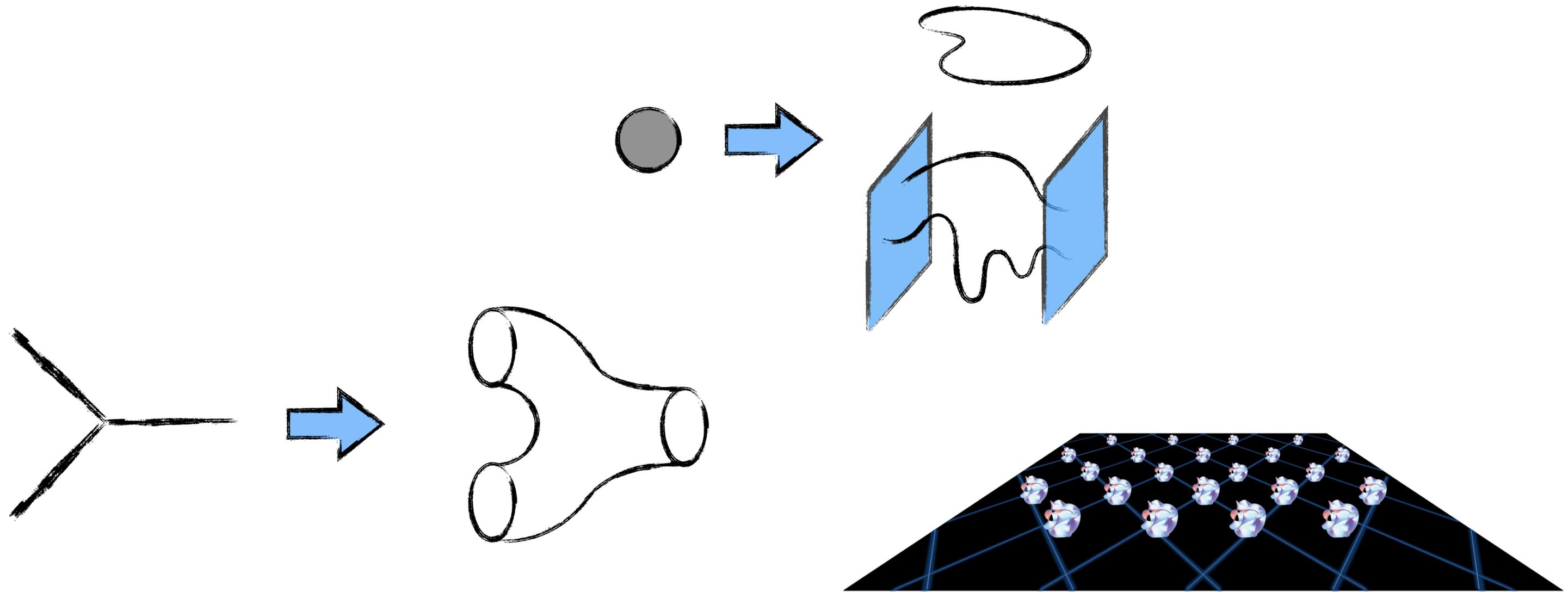
...however, we need a unified description to study physics at high energies



What happened at the Big Bang?
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What happens at the event horizon of a black hole?

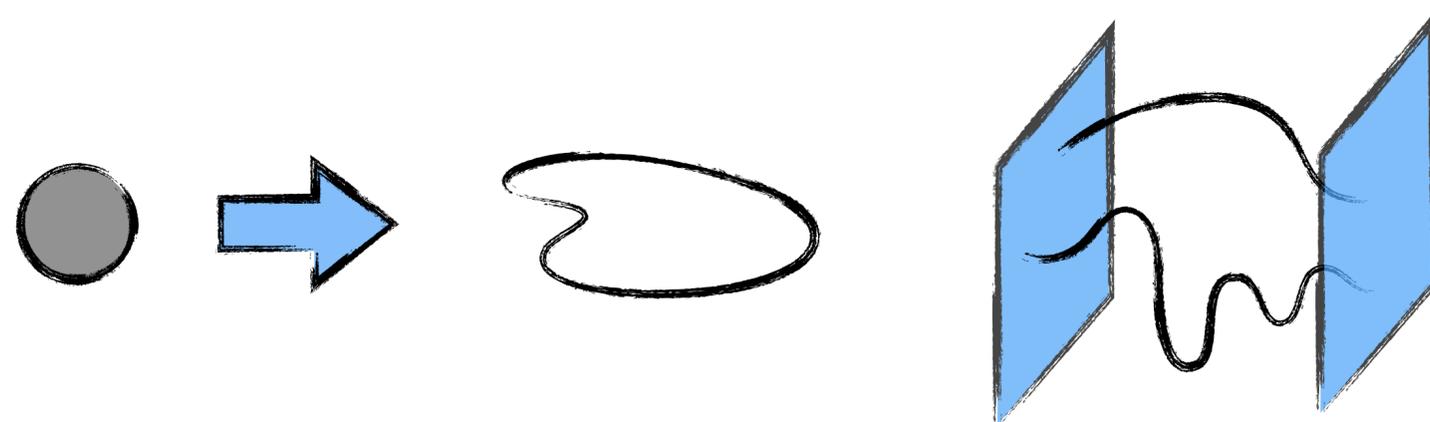
Do all particles and forces come from a Grand Unified Theory?



Introduction to String Theory

String Theory

- ▶ One promising candidate for a unified description of General Relativity and Quantum Field Theory: **String Theory**
- ▶ Basic assumption: Fundamental constituents of the particles that mediate the four forces and of all matter are not-point-like, but one-dimensional, extended strings



String Theory - Compactifications

This has far-reaching consequences!

- ▶ Requires ten space-time dimensions

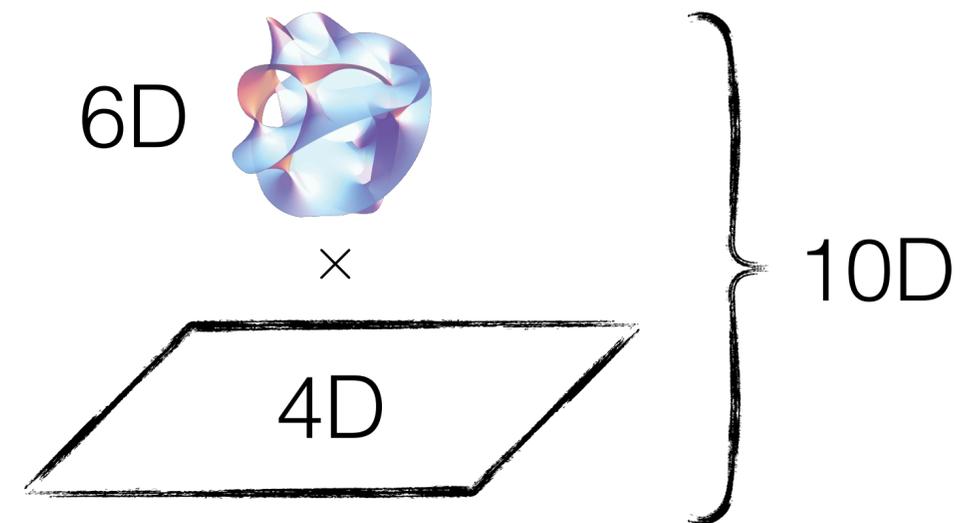
“... last time I checked the world
was 3D”

String Theory - Compactifications

This has far-reaching consequences!

- ▶ Requires ten space-time dimensions

- ▶ We only observe 3, so 6 have to be small to evade detection \Rightarrow compactifications



- ▶ The equations of motion put stringent constraints on the compactification geometry. The compact 6D space has to be a Calabi-Yau manifold

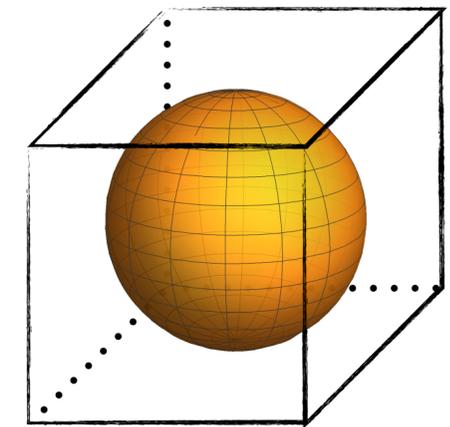
“...ok, but how do we describe the extra dimensions?”

Description of compact extra dimensions

- ▶ It is often easier to describe spaces inside larger ambient spaces:

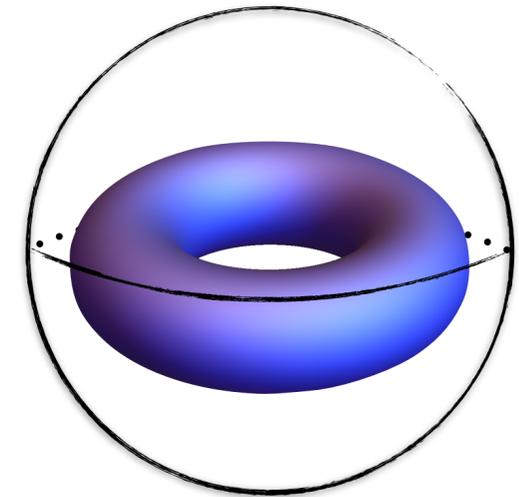
Sphere S^2 inside \mathbb{R}^3 : $x^2 + y^2 + z^2 = R^2$

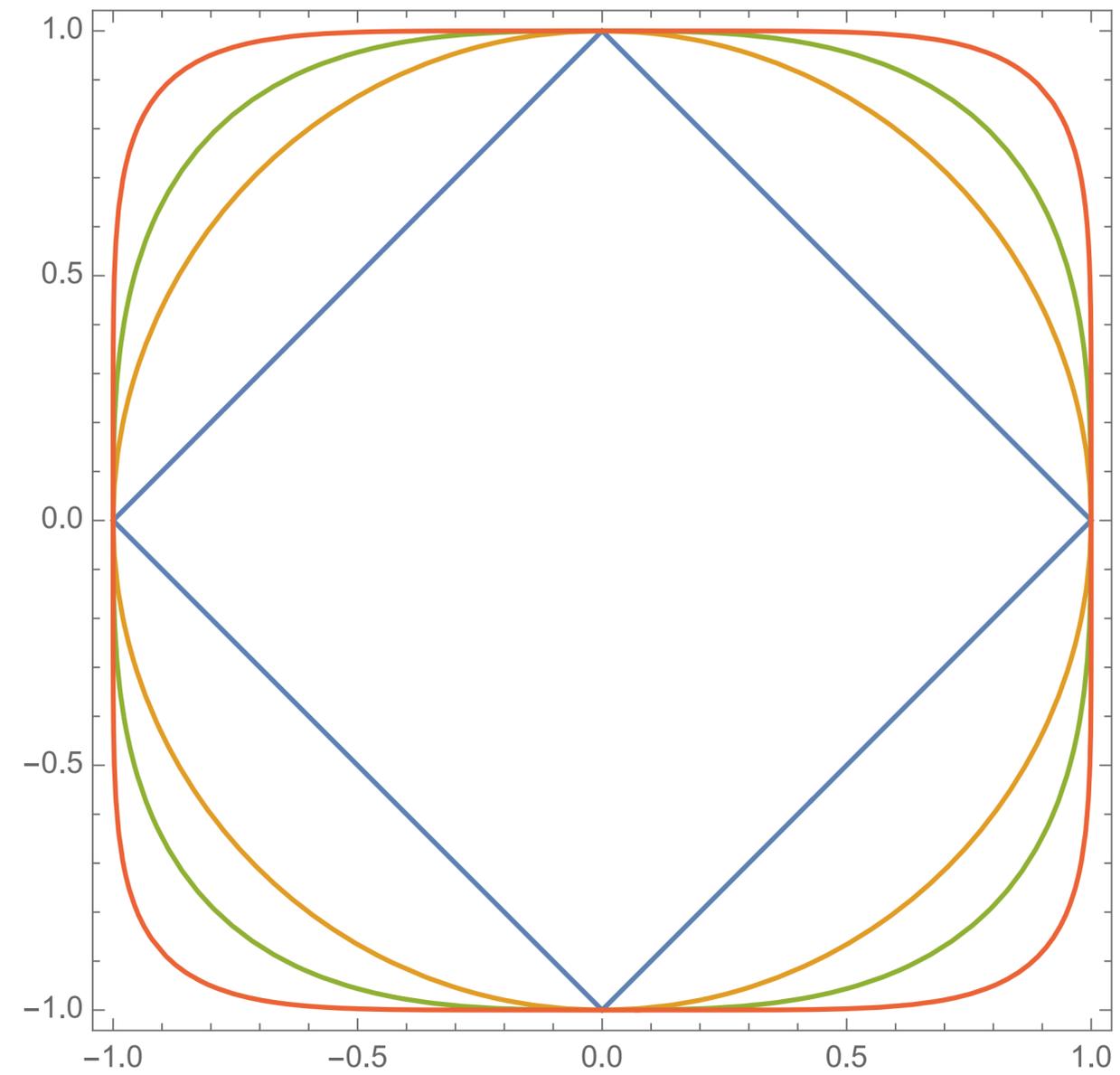
Radius \nearrow



Torus T^2 inside \mathbb{P}^2 : $x^3 + y^3 + z^3 = \psi xyz$

Shape \nearrow





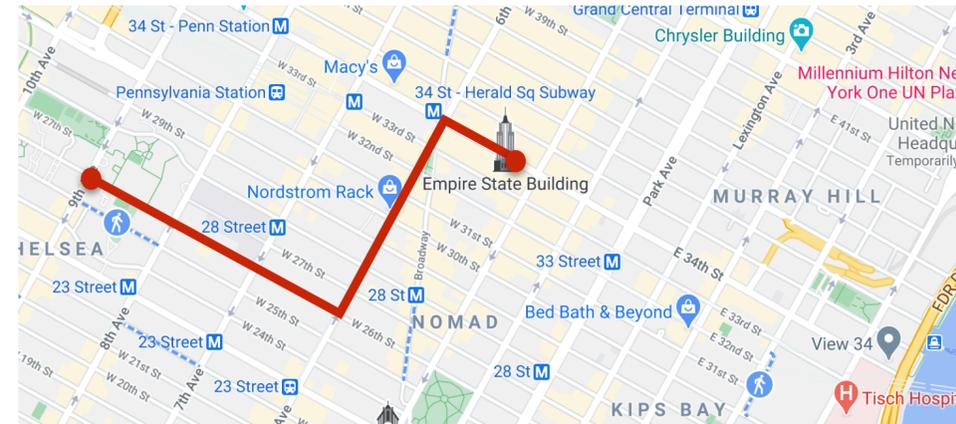
Metrics

Metrics

- ▶ Metrics measure distances, but the choice is not unique



[Source: wikipedia]



[Source: google maps]

Metrics

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[Source: wikipedia]

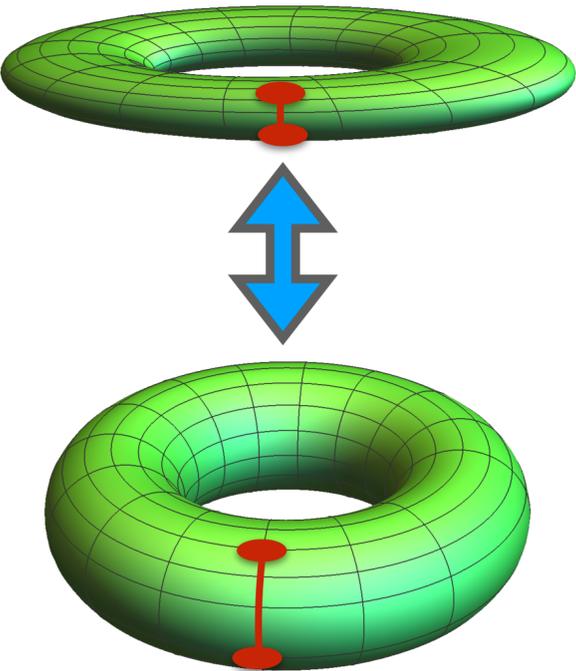
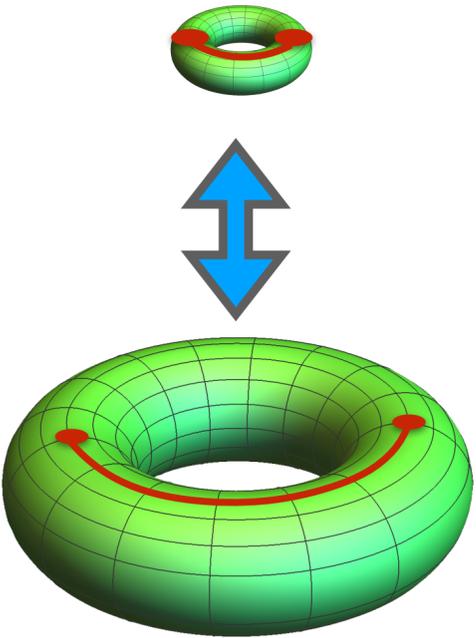


[Source: google maps]

- ▶ If space is curved, metric depends on the point you are at. It also depends on volume/shape



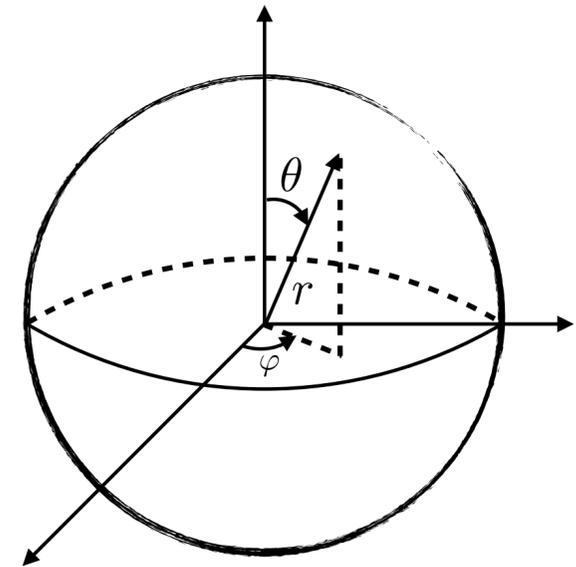
[Photo Credit: Jimmy Chin]



Metrics and integration

- ▶ Consider e.g. spherical coordinates

$$ds^2 = dr^2 + r^2 d\theta^2 + r^2 \sin^2 \theta d\varphi^2 \quad \Rightarrow \quad g_{ab} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & r^2 & 0 \\ 0 & 0 & r^2 \sin^2 \theta \end{pmatrix}$$



- ▶ From this we can compute the volume of the 3D ball B^3

$$\int_{B^3} dV = \int_0^R \int_0^\pi \int_0^{2\pi} r^2 \sin \theta dr d\theta d\varphi, \quad dV = \sqrt{\det g} dr d\theta d\varphi$$

Think of a metric g as a function

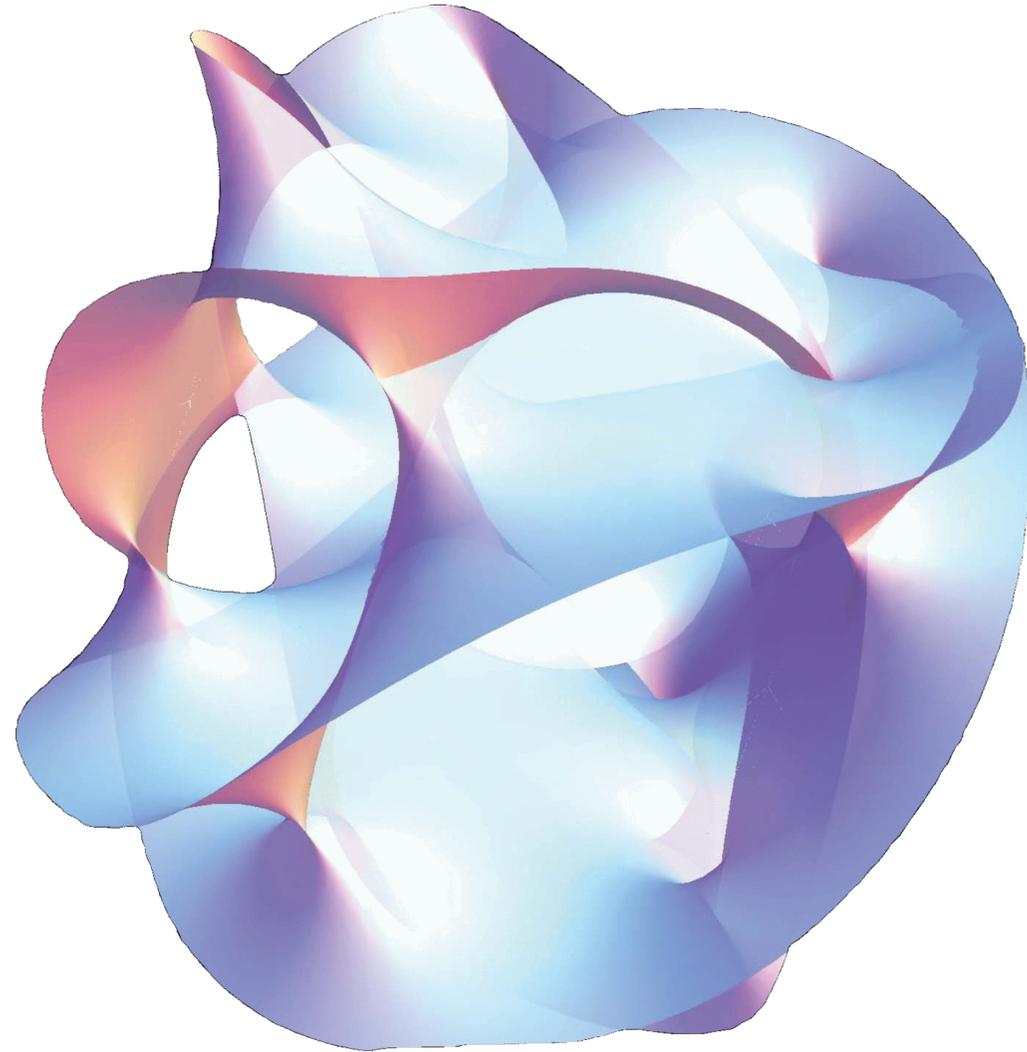
$$g: \text{position} \times \text{volume} \times \text{shape} \rightarrow \mathbb{R}^{d \times d}$$

and optimize a NN to represent this function

Calabi-Yau Metrics

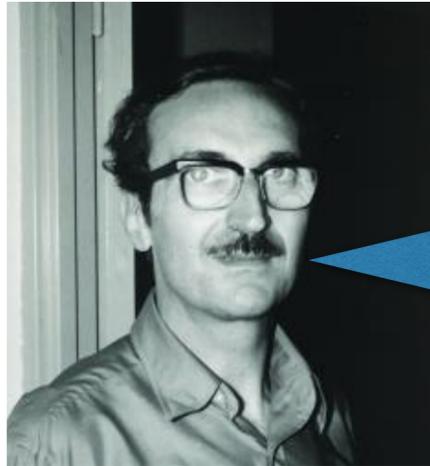
- ▶ Calabi-Yau spaces are spaces on which a metric exists that is “flat enough”, i.e. their Ricci tensor vanishes

$$\begin{aligned}
 R_{ij} = & -\frac{1}{2} \sum_{a,b=1}^n \left(\frac{\partial^2 g_{ij}}{\partial x^a \partial x^b} + \frac{\partial^2 g_{ab}}{\partial x^i \partial x^j} - \frac{\partial^2 g_{ib}}{\partial x^j \partial x^a} - \frac{\partial^2 g_{jb}}{\partial x^i \partial x^a} \right) g^{ab} \\
 & + \frac{1}{2} \sum_{a,b,c,d=1}^n \left(\frac{1}{2} \frac{\partial g_{ac}}{\partial x^i} \frac{\partial g_{bd}}{\partial x^j} + \frac{\partial g_{ic}}{\partial x^a} \frac{\partial g_{jd}}{\partial x^b} - \frac{\partial g_{ic}}{\partial x^a} \frac{\partial g_{jb}}{\partial x^d} \right) g^{ab} g^{cd} \\
 & - \frac{1}{4} \sum_{a,b,c,d=1}^n \left(\frac{\partial g_{jc}}{\partial x^i} + \frac{\partial g_{ic}}{\partial x^j} - \frac{\partial g_{ij}}{\partial x^c} \right) \left(2 \frac{\partial g_{bd}}{\partial x^a} - \frac{\partial g_{ab}}{\partial x^d} \right) g^{ab} g^{cd} \\
 = & 0
 \end{aligned}$$



Introduction to Calabi-Yau manifolds

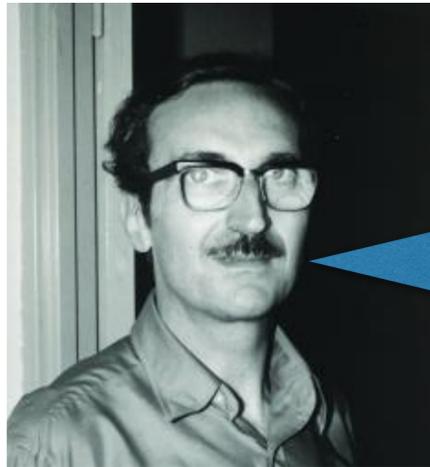
CY metrics - Existence and Uniqueness



[Calabi '54]

If some topological conditions are satisfied, I conjecture a Ricci-flat metric exists. I cannot prove that it exists, but I know it will be unique.

CY metrics - Existence and Uniqueness



[Calabi '54]

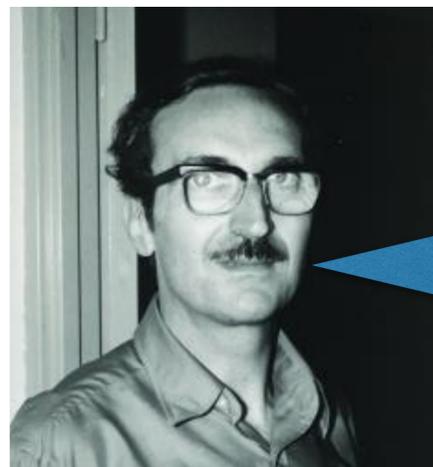
If some topological conditions are satisfied, I conjecture a Ricci-flat metric exists. I cannot prove that it exists, but I know it will be unique.

I can prove that such a metric exists, but I can neither tell you what it looks like nor how to construct it.



[Yau '77]

CY metrics - Existence and Uniqueness



[Calabi '54]

If some topological conditions are satisfied, I conjecture a Ricci-flat metric exists. I cannot prove that it exists, but I know it will be unique.

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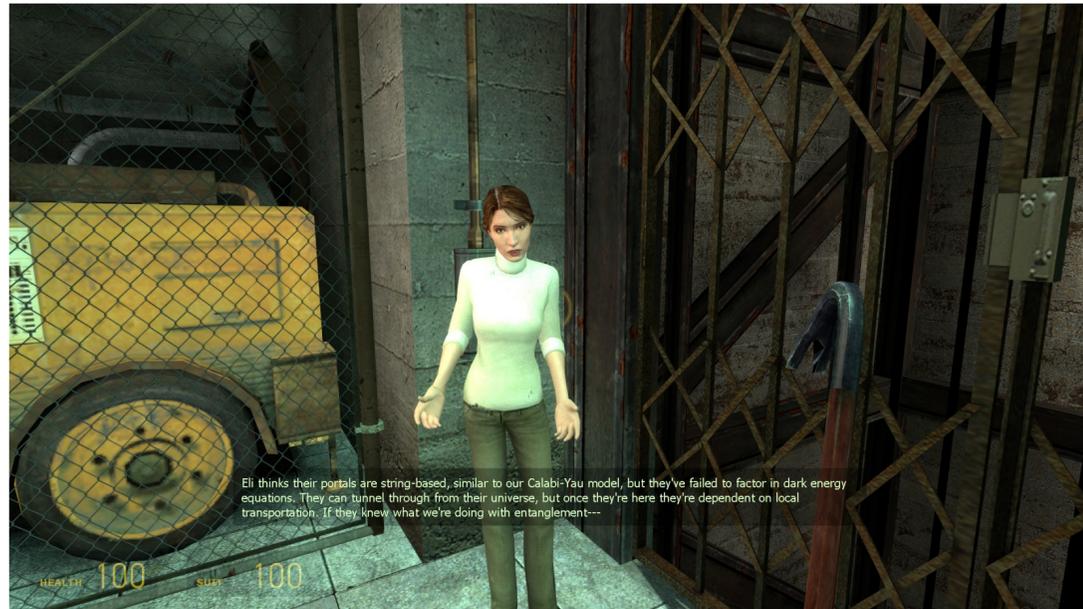
Great, take my medal!



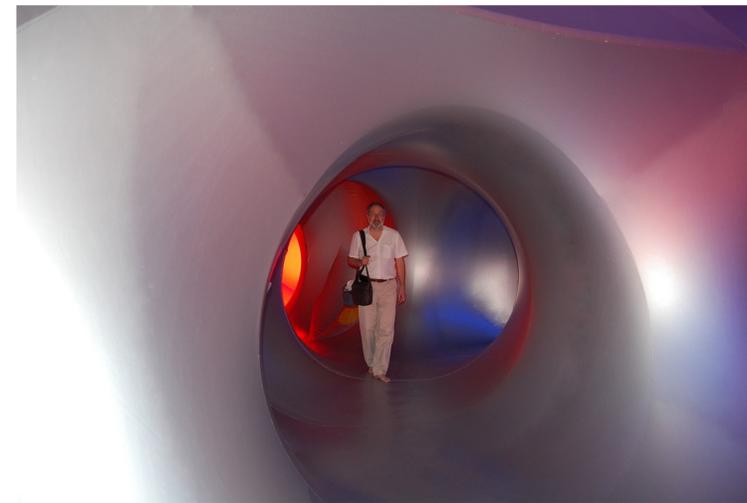
[Fields '82]

... even now, 40 years later, we still
don't know the geometry of the
space-time we live in

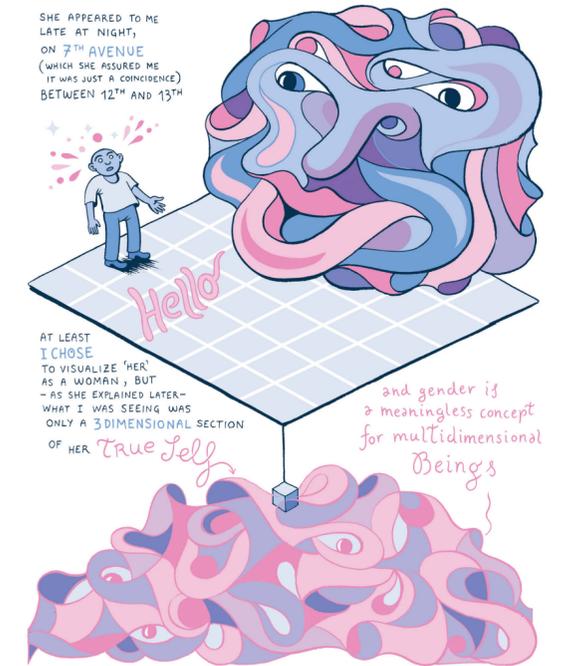
Calabi-Yaus in pop culture



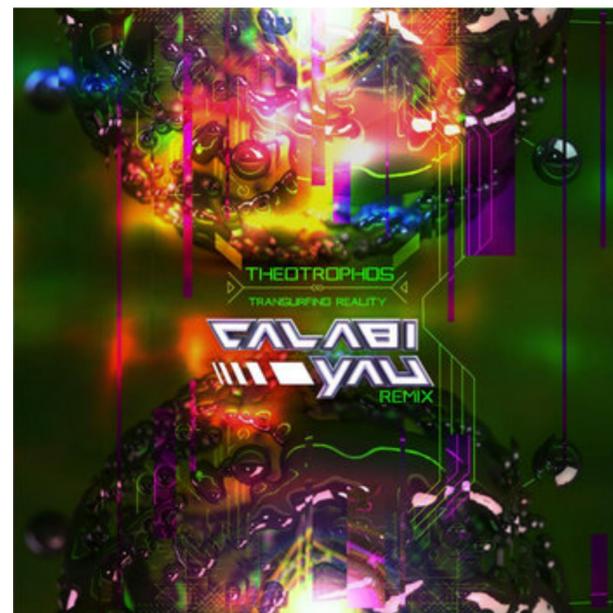
[Source: Half-Life 2]



[Source: wikipedia]



[Source: matteofarinella.com]

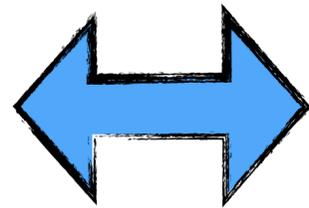
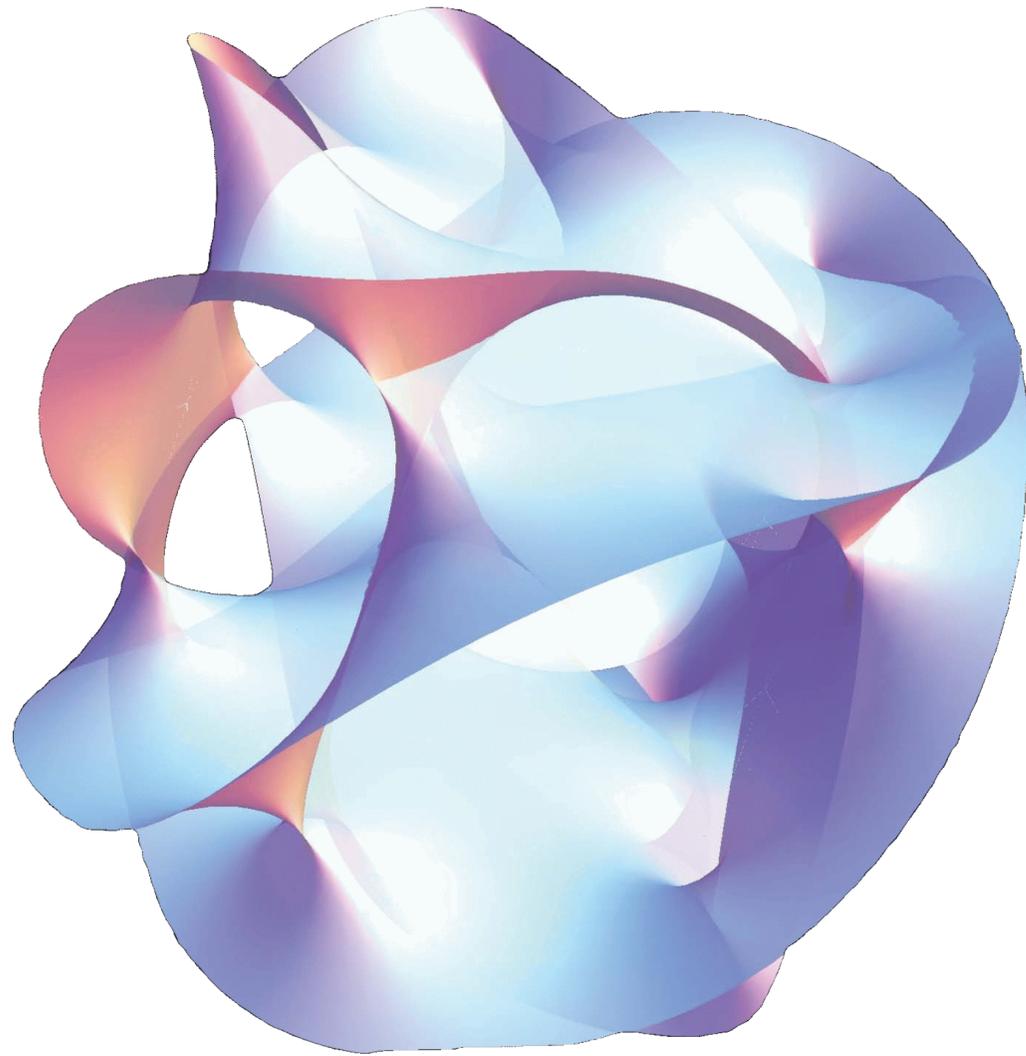


[Source: soundcloud.com]



[Source: tfwiki.net]

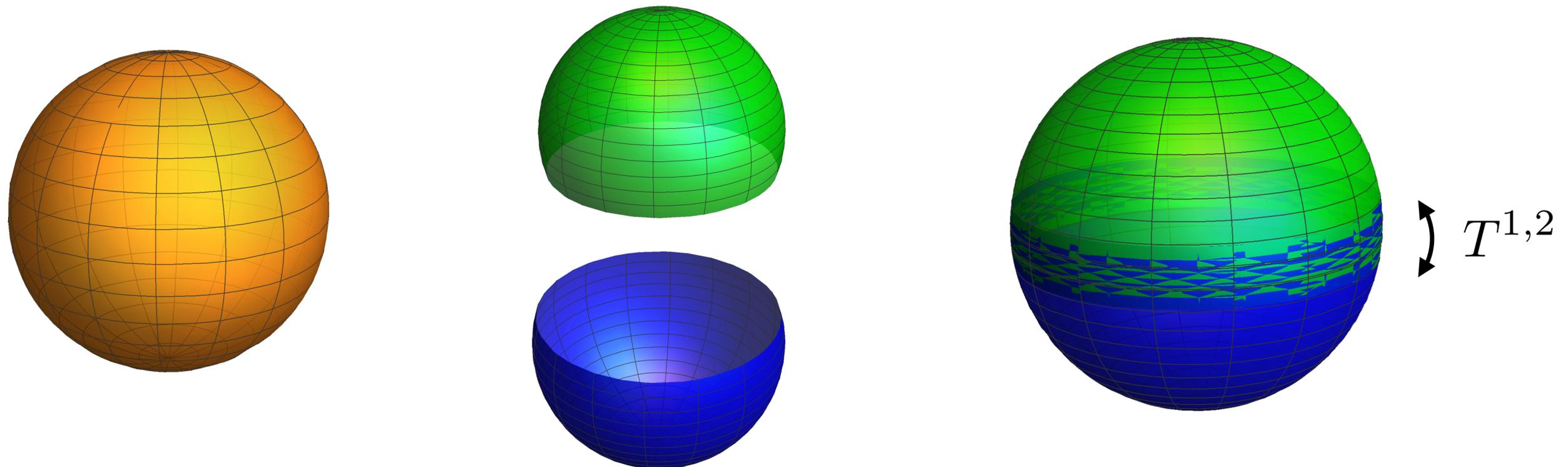
Calabi-Yau manifolds - Properties



- Complex
- Kähler
- Ricci-flat

CY Property 1 - Complex

- ▶ In general manifolds cannot be covered by a single patch
- ▶ On each patch, one can choose a local description, coordinate system, etc. But one must make sure that the descriptions can be matched on the overlap and everything can be patched to a complex manifold globally (e.g. choice $i = \sqrt{-1}$ vs $i = -\sqrt{-1}$, ...)



CY Property 2 - Kähler

- ▶ The space must be Kähler
- ▶ This means that the metric can be written in terms of derivatives of a real, scalar function called the **Kähler potential** K

$$g_{a\bar{b}} = \frac{\partial}{\partial z^a} \frac{\partial}{\partial \bar{z}^b} K, \quad J = \frac{i}{2} \sum_{a < b} g_{a\bar{b}} \varepsilon^{a\bar{b}} dz^a d\bar{z}^b, \quad z = x + iy, \quad \bar{z} = x - iy$$

Kähler potential  Kähler form 

- ▶ In general, integrating the metric to find the Kähler potential is hard. So one can either start with a Kähler potential and derive the metric, or one has to solve the differential equation $\frac{\partial J}{\partial z^a} = \frac{\partial J}{\partial \bar{z}^b} = 0$.

CY Property 3 - Ricci-flat

- ▶ The CY metric needs to have Ricci tensor 0
- ▶ The Ricci tensor involves two derivatives of the metric, which itself involves 2 derivatives of K
- ▶ This fourth-order partial differential equation is extremely hard to solve

- ▶ We can improve on this. On a CY, one can write down

$$J = \frac{i}{2} \sum_{a < b} g_{a\bar{b}} \varepsilon^{a\bar{b}} dz^a d\bar{z}^{\bar{b}} \quad \Rightarrow \quad J^3 = -\frac{i}{8} \sqrt{\det g} dz_1 d\bar{z}_1 dz_2 d\bar{z}_2 dz_3 d\bar{z}_3$$

$$\Omega = \left(\frac{\partial p}{\partial z_4} \right)^{-1} dz_1 dz_2 dz_3 \quad \Rightarrow \quad |\Omega|^2 = \left| \frac{\partial p}{\partial z_4} \right|^{-2} dz_1 dz_2 dz_3 d\bar{z}_1 d\bar{z}_2 d\bar{z}_3$$

- ▶ Since the volume form is unique (up to a constant): $J^3 = \kappa |\Omega|^2$
- ▶ This leads to a second-order PDE of Monge-Ampere type

CY manifolds - simplest example

Let us illustrate the construction of CY manifolds. We start in 2D, i.e. with a torus.

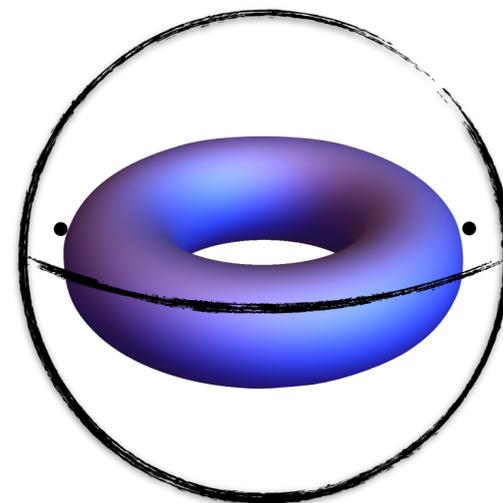
- ▶ First, we start with a complex Kähler ambient space \mathbb{P}^2

$$\mathbb{P}^2 = \{(z_0, z_1, z_2) \in \mathbb{C}^3 \mid (z_0, z_1, z_2) \sim (\lambda z_0, \lambda z_1, \lambda z_2), \quad \lambda \in \mathbb{C}\}$$

- ▶ This ambient space is clearly complex. It is also Kähler, and a canonical metric is the Fubini-Study metric derived from the Kähler potential

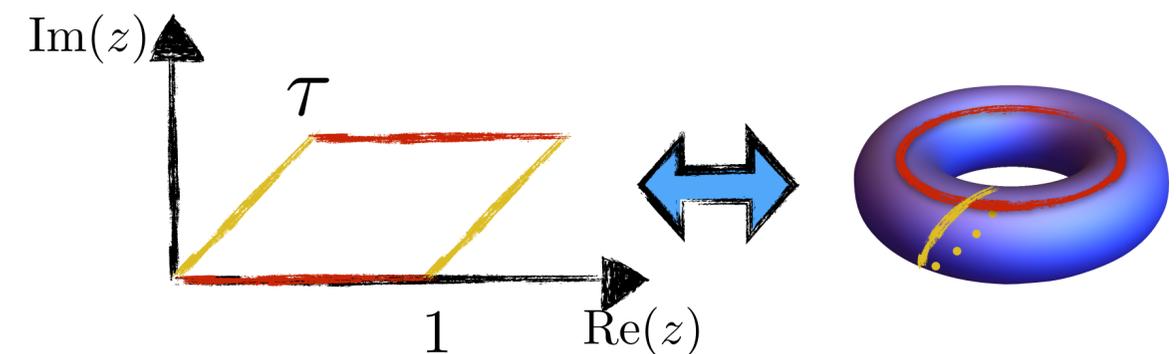
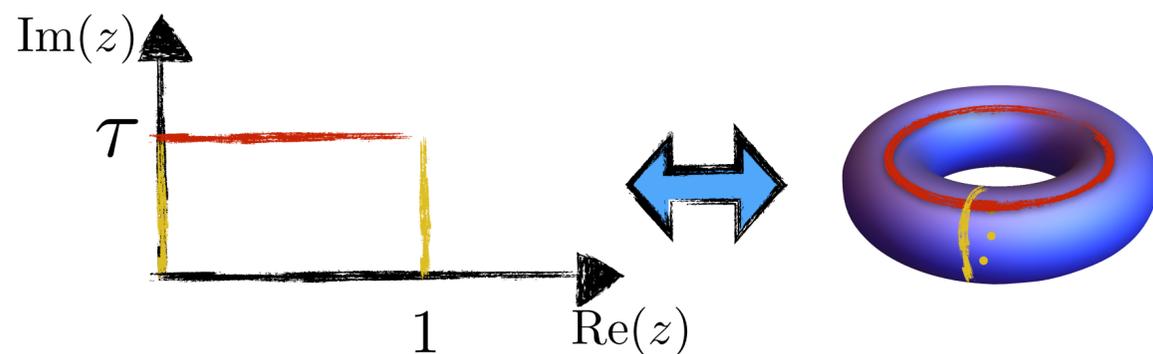
$$K = \log(|z_0|^2 + |z_1|^2 + |z_2|^2)$$

- ▶ Now we describe the torus as a complex 1D surface inside \mathbb{P}^2



CY manifolds - simplest example

- ▶ $\text{tr}(R) = 0$ iff the equation is homogeneous of degree 3 in z_0, z_1, z_2
- ▶ Take e.g. $p = z_0^3 + z_1^3 + z_2^3 + \psi z_0 z_1 z_2 \stackrel{!}{=} 0$
- ▶ The torus is a 1D CY manifold. But inheriting the ambient FS metric does not lead to a Ricci-flat metric on the torus.
- ▶ However, the torus can also be described as $\{z \in \mathbb{C} \mid z \sim z + 1 \sim z + \tau\}$

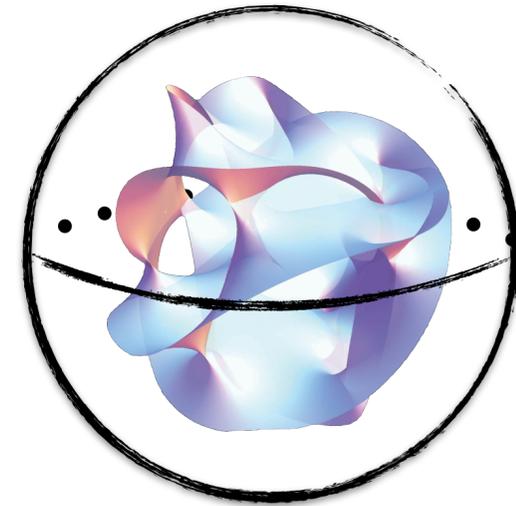


- ▶ The parameter τ describes the tilting (shape) of the torus and is related to the parameter ψ . These parameters are called complex structure parameters and are a priori not fixed.

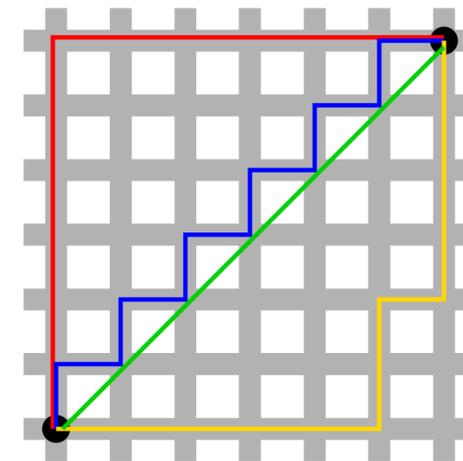
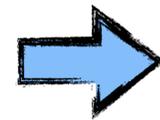
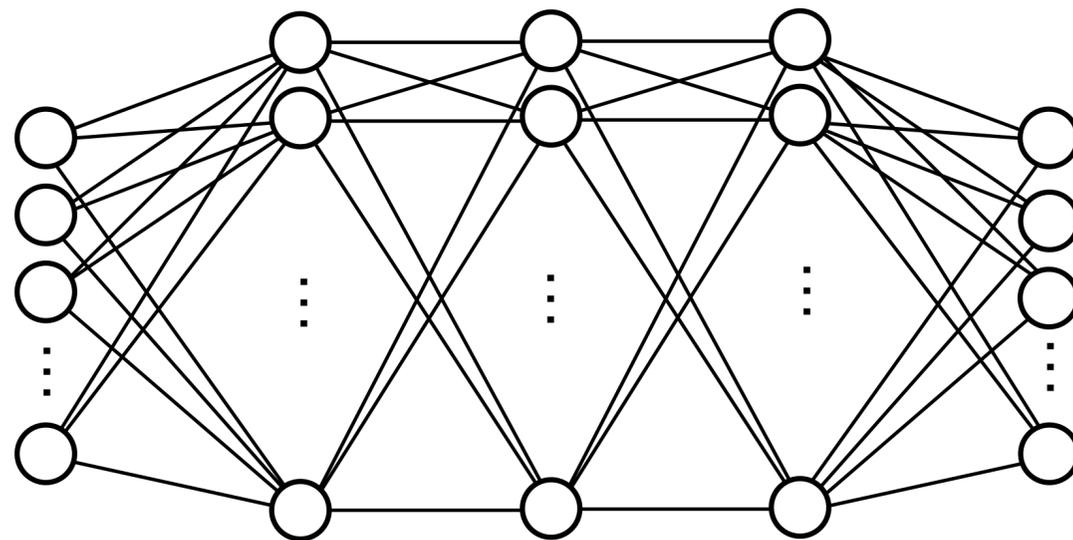
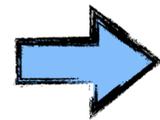
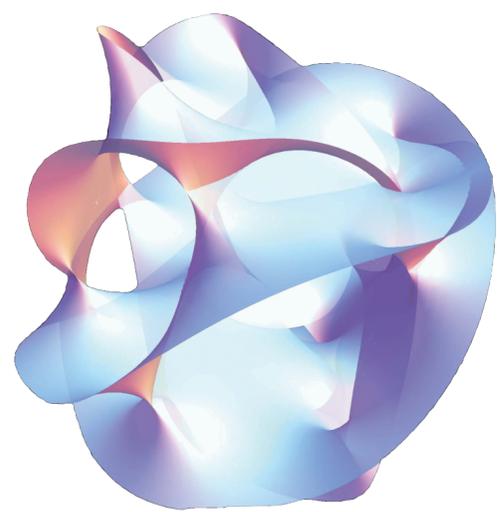
CY manifolds - simplest 6D example

- ▶ The same construction carries over to 3-folds. Start with a quintic equation in \mathbb{P}^4 :

$$p = z_0^5 + z_1^5 + z_2^5 + z_3^5 + z_4^5 + \psi z_0 z_1 z_2 z_3 z_4 \stackrel{!}{=} 0$$



- ▶ Again, this manifold is complex, Kähler and has $\text{tr}(R) = 0$, so a Ricci-flat metric does exist by Yau's theorem
- ▶ The parameter ψ encodes the complex structure of the CY manifold
- ▶ While we do not know the Ricci-flat metric, we can readily construct Ω



ML for Calabi-Yau metrics

Steps

Find points
on CY

Optimize NN

- Overlap
- Kahler
- Ricci-flat

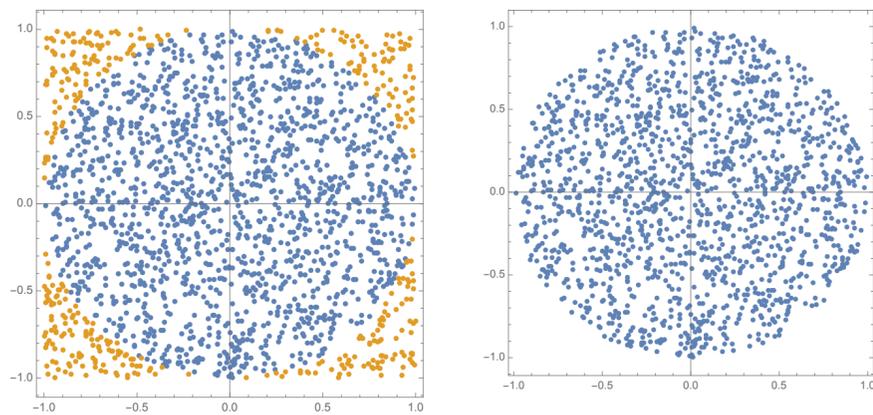
Repeat for
different
shapes and
volumes

CY metric

1. Sampling points

Random sampling depends on the metric. Take a disk $x = r \cos \varphi$, $y = r \sin \varphi$

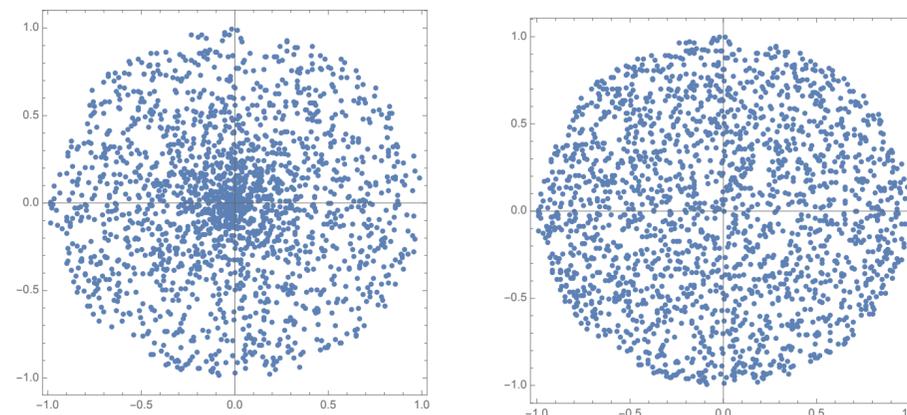
Rejection sampling



$$x \in [-1, 1], y \in [-1, 1]$$

Reject samples that are not on the manifold

Random sampling

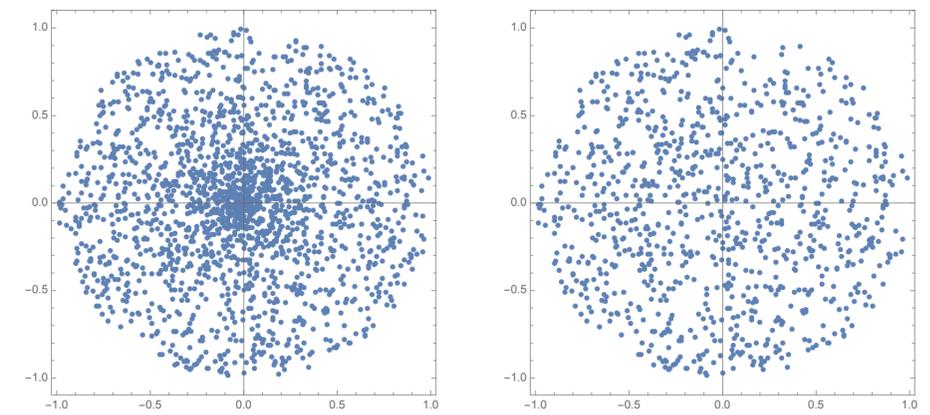


$$r \in [0, 1], \varphi \in [0, 2\pi]$$

$$r^2 \in [0, 1], \varphi \in [0, 2\pi]$$

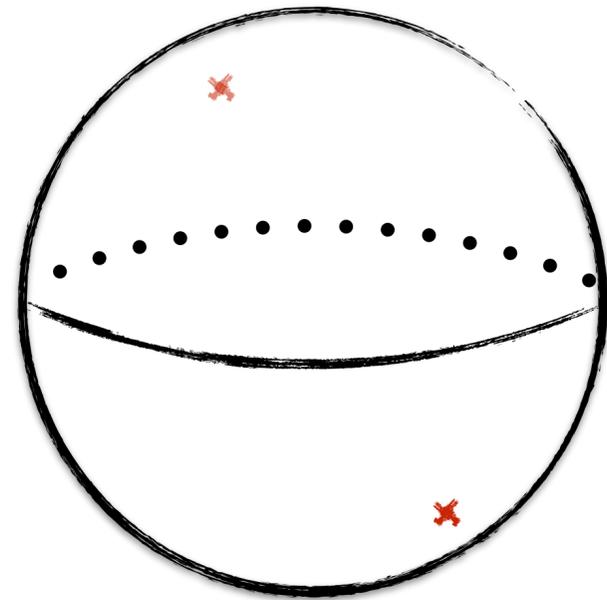
Sample w.r.t. correct measure

Resampling

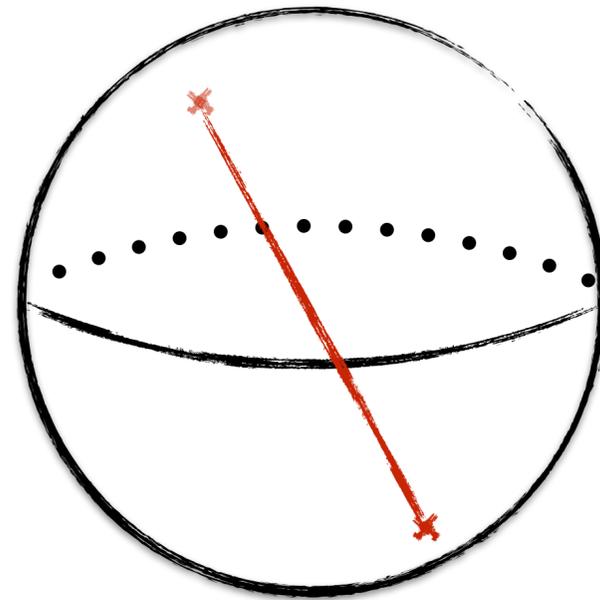


- Find points w.r.t. wrong measure
- Assign weight to each point
- Draw points with prior given by these weights
- Alternatively, use all points and weight the loss by the weights

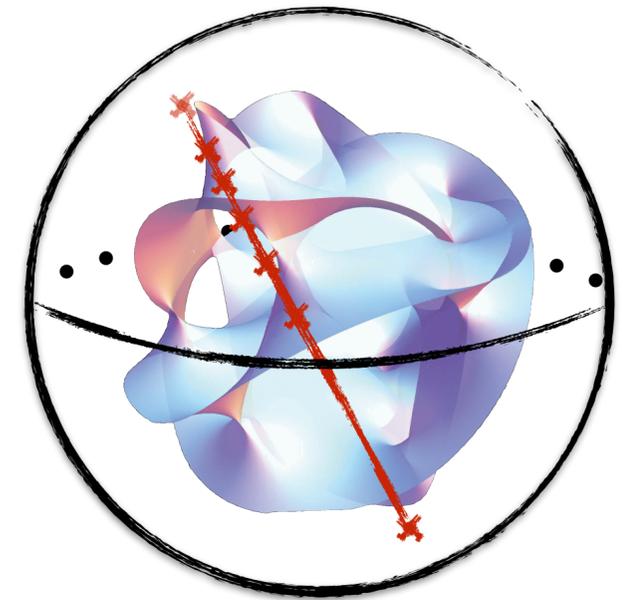
1. Find points on CY



Sample points from a sphere inside \mathbb{P}^4



Find the line through these ambient points



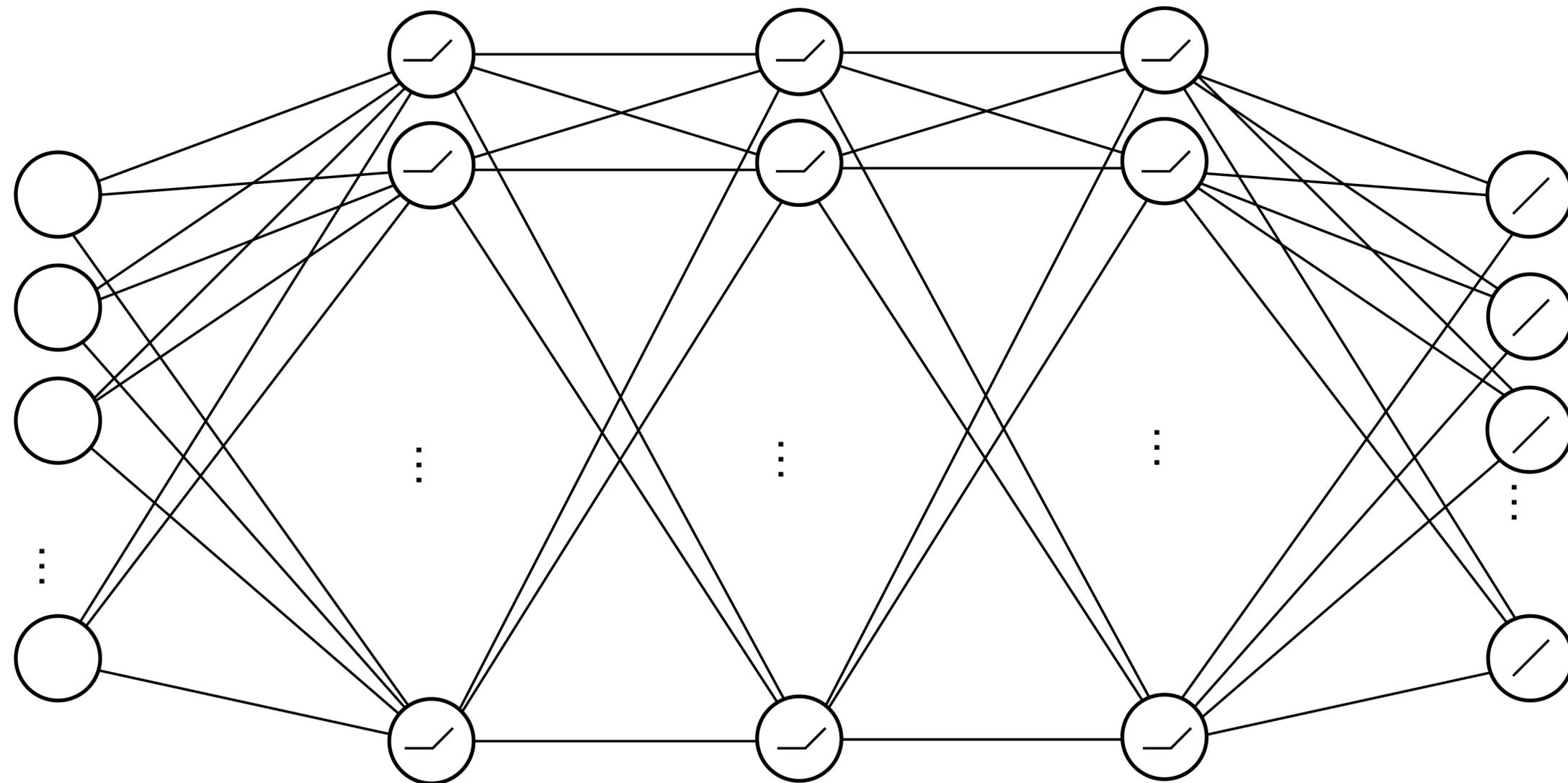
Intersect the CY eqn with the line \Rightarrow 5 solns.

Then, the weights for a “uniform” sampling on the CY are given by $w = \frac{|\Omega|^2}{J_{\text{FS}}^3}$

2. Setup the NN

- ▶ Input of the NN:
 - The point on the CY (5 complex coordinates \Rightarrow 10 input nodes)
 - The patch in which to evaluate the NN (a 5D vector in $[0, 1]^{\times 5}$ with all 0 and a 1 at position i to indicate the patch $z_i \neq 0$)
 - The point in CS space at which to compute the metric (2 real coordinates \Rightarrow 2 input nodes)
- ▶ Output of the NN: The independent component of the hermitian metric (3 real dof's on the diagonal, 3 complex off-diagonal dof's \Rightarrow 9 output nodes)

2. Setup the NN



\mathbb{R}^{17}

\mathbb{R}^{100}

\mathbb{R}^{100}

\mathbb{R}^{100}

\mathbb{R}^9

Leaky ReLU activation function

Identity activation function

2. Setup the NN

1. Take the pullback of the FS metric and learn the CY metric as a correction:

$$g_{\text{CY}} = g_{\text{FS}}(\mathbb{1} + g_{\text{NN}})$$

2. Tune the NN parameters such that the metric satisfies at all points:

(i) Overlap: $g_{\text{CY}}^{(i)} = T_{i,j} g_{\text{CY}}^{(j)} T_{i,j}^\dagger \Rightarrow L_1 = \sum_{\text{points}} \sum_{i,j} \sum_{a,b} \left[(g_{\text{CY}}^{(i)} - T_{i,j} g_{\text{CY}}^{(j)} T_{i,j}^\dagger)_{ab} \right]^2$

(ii) Kähler: $\partial_a J = \bar{\partial}_{\bar{b}} J = 0 \Rightarrow L_2 = \sum_{\text{points}} \sum_a \sum_{i,\bar{j}} [\partial_a J_{i\bar{j}} - \partial_i J_{a\bar{j}}]^2 + \sum_{\text{points}} \sum_{\bar{b}} \sum_{i,\bar{j}} [\partial_{\bar{b}} J_{i\bar{j}} - \partial_{\bar{j}} J_{a\bar{b}}]^2$

(iii) Monge-Ampere equation: $J^3 = \kappa |\Omega|^2 \Rightarrow L_3 = \sum_{\text{points}} \sigma^2$, $\sigma := \left| 1 - \frac{J^3}{|\Omega|^2} \right|$

3. The overall loss is $L_{\text{tot}} = \lambda_1 L_1 + \lambda_2 L_2 + \lambda_3 L_3$

We perform a box search over the hyperparameters λ_i and choose $\lambda_3 = 10$, $\lambda_1 = \lambda_2 = 1$

2. Setup the NN

- ▶ The result does not depend crucially on the NN architecture/activation function (ReLU, Tanh, GELU)
- ▶ We train the NN with 50'000 points per ψ for $\text{Re}(\psi), \text{Im}(\psi) \in [-100, 100]$.
 - We use a batch size of 900 and ADAM optimizer, train for 20 epochs
 - Adding more points does improve the accuracy
- ▶ We use an evaluation set of 5'000 points
- ▶ We also tried training longer and including measures to prevent overfitting (batch normalization, dropout layers, early stopping), but this did not improve the result
- ▶ We implemented this in PyTorch and Tensorflow
- ▶ We need derivatives of the NN w.r.t. input as well as w.r.t. parameters
 - No direct backward hooks in PyTorch 1.6
 - Bug in TF 2.4 with 2 gradient tapes and pfor

2. Setup the NN

- ▶ We need derivatives of the NN w.r.t. input as well as w.r.t. parameters
 - No direct backward hooks in PyTorch 1.6

```
def get_jacobian_reim(self, y, x):
    jacobian = []

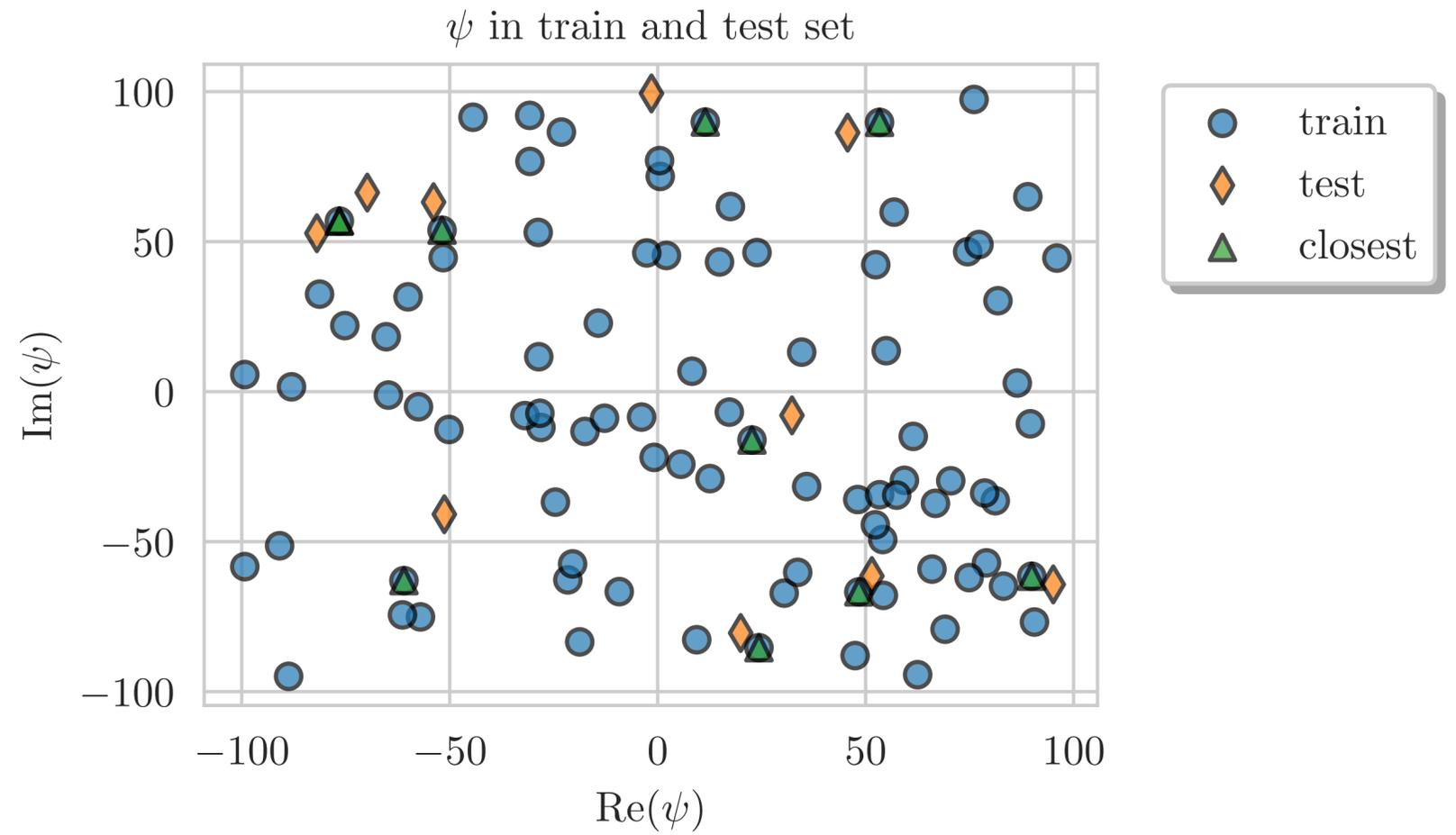
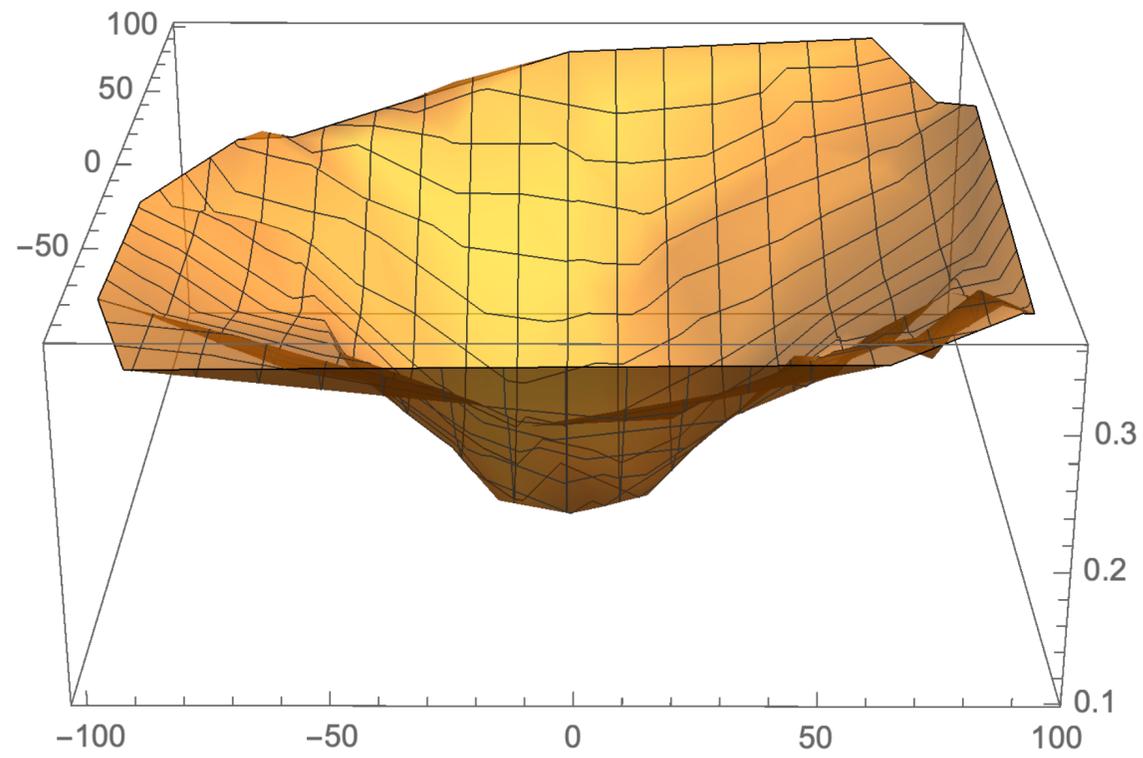
    for i in range(y.shape[-1]):
        v = torch.zeros_like(y)
        v[:, i] = 1.
        dy_i_dx = torch.autograd.grad(y, x, grad_outputs=v, create_graph=True, retain_graph=True)[0]
        dy_i_dx = dy_i_dx[:, :2 * self.dim_a]
        jacobian.append(dy_i_dx)

    jacobian = torch.stack(jacobian, dim=2).requires_grad_()
    return self.jacs_to_re_im(jacobian)
```

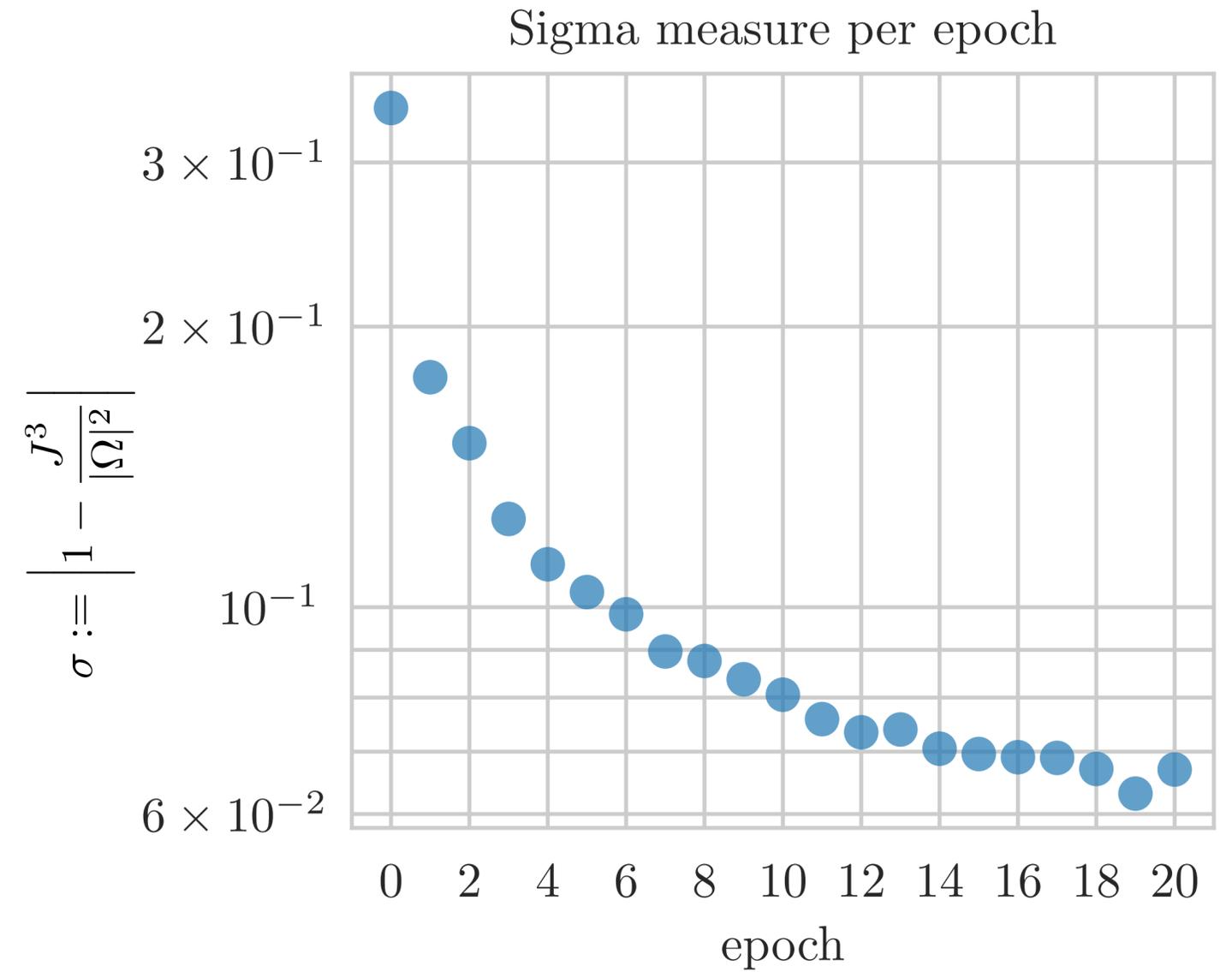
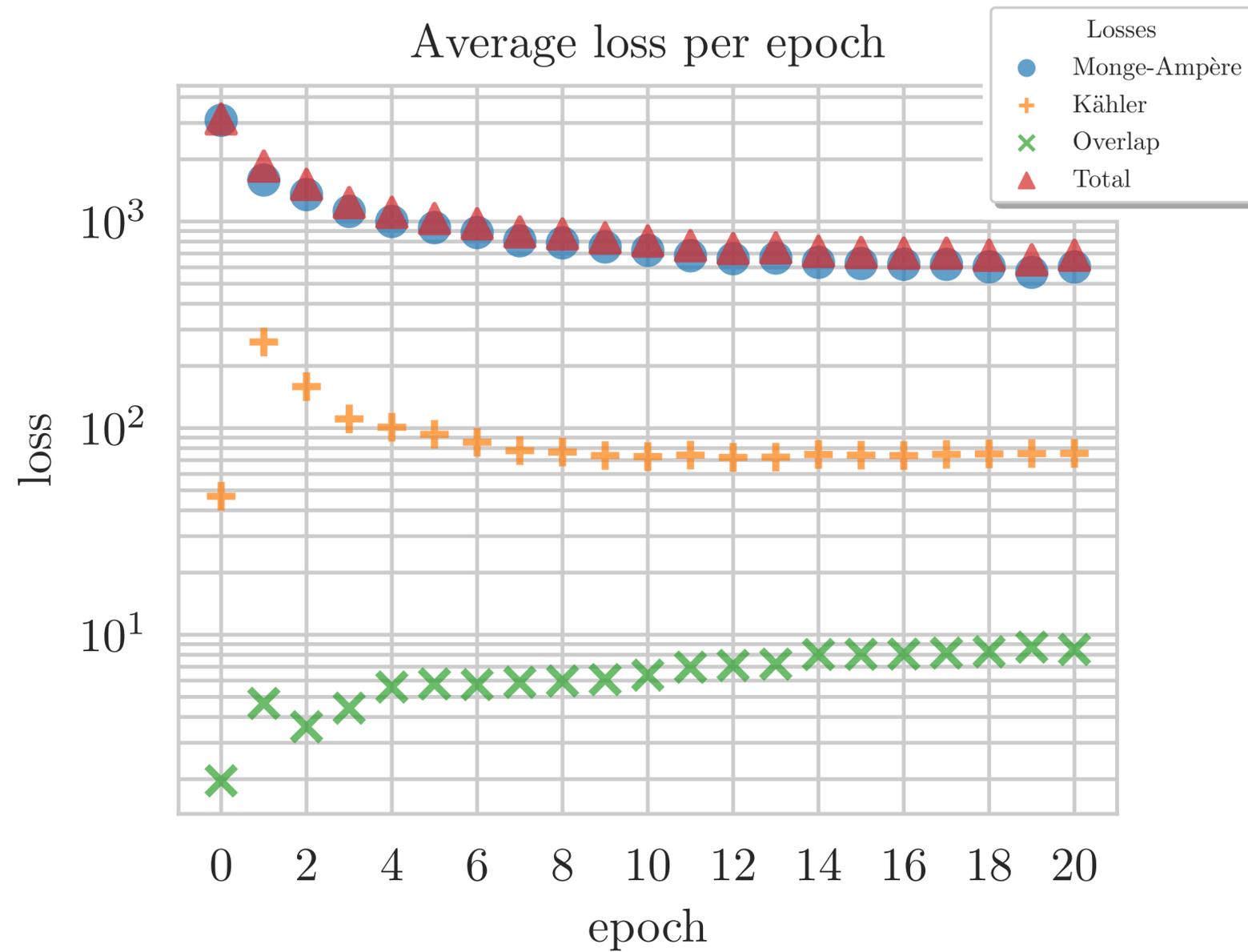
- Bug in TF 2.4 with 2 gradient tapes and pfor

```
def get_jacobian_reim(self, y, x):
    with tf.GradientTape(persistent=True, watch_accessed_variables=True) as t1:
        with tf.GradientTape(persistent=True, watch_accessed_variables=True) as t2:
            t2.watch(x)
            y_pred = fsmodel.pullbacks(x)[::,3] * y
            batch_jac = t2.batch_jacobian(y_pred, x)
```

3. Learn the metric

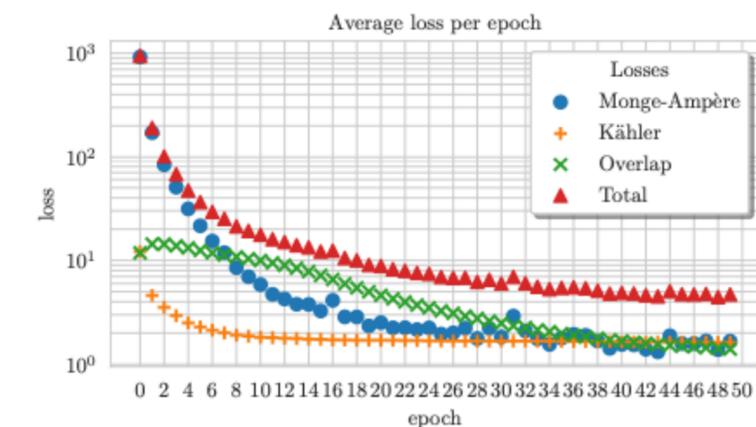
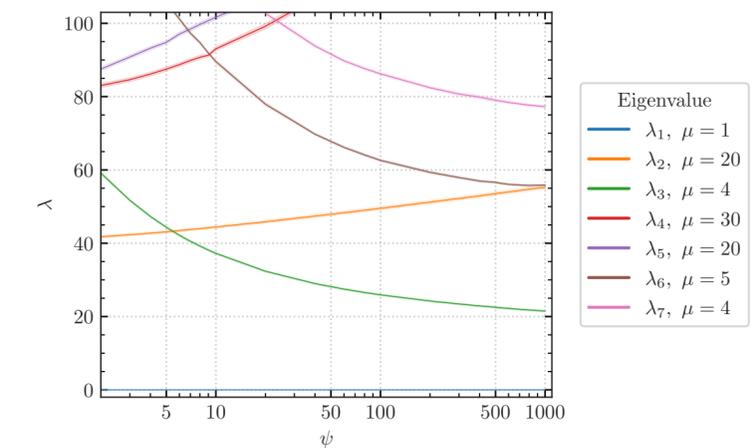
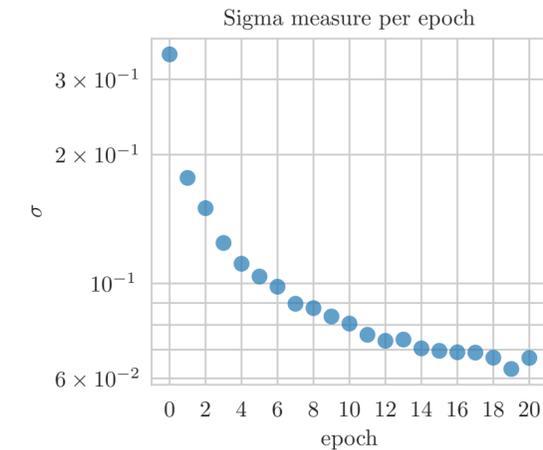


3. Learn the metric



Conclusions

- ▶ NNs can learn the moduli- (and position-) dependent CY metric by optimizing the underlying differential equations
- ▶ This has many applications in Physics (massive string modes, swampland conjectures, Yukawa couplings) and Mathematics (SYZ conjecture)
- ▶ The methods generalize to $SU(n)/G_2$ structure



Conclusions

- ▶ NNs can learn the moduli- (and position-) dependent CY metric by optimizing the underlying differential equations

- ▶ This h
string
coupl

Thank you for your
attention!

- ▶ The methods generalize to $SU(n)/G_2$ structure

